

On Periodic Solutions of N-Vortex Problem

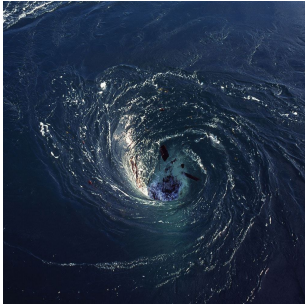


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Geometry and Dynamics in
Interaction
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1. VORTEX PROBLEM AS A HAMILTONIAN SYSTEM

Vortices as we might see in real life:



(a) A vortex in Atlantic Ocean



(b) The Jupiter Red Spot



(c) When One flushes the Toilet

Figure 1: Some Examples of Vortices

- The study of vortices goes back to Helmholtz since 1858



Figure 2: Hermann Von Helmholtz, 1821-1894

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Figure 2: Hermann Von Helmholtz, 1821-1894

- Its Hamiltonian structure is first formulated by Kirchhoff in 1876

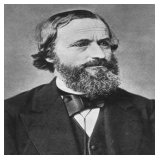


Figure 3: Gustav Robert Kirchhoff, 1824-1887

- Let $z_i = (x_i, y_i)$ denotes the position of i -th vortex in the plane, with a given vorticity Γ_i .

Hamiltonian Structure of Vortex Dynamics

- Let $z_i = (x_i, y_i)$ denotes the position of i -th vortex in the plane, with a given vorticity Γ_i .
- Their movements are governed by the System

$$\begin{cases} \Gamma_i \dot{x}_i(t) = \frac{\partial H}{\partial y_i} \\ \Gamma_i \dot{y}_i(t) = -\frac{\partial H}{\partial x_i} \end{cases} \quad (1)$$

with

$$H = -\frac{1}{4\pi} \sum_{1 \leq i < j \leq N} \Gamma_i \Gamma_j \log |z_i - z_j|^2$$

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with

$$H = -\frac{1}{4\pi} \sum_{1 \leq i < j \leq N} \Gamma_i \Gamma_j \log |z_i - z_j|^2$$

- The energy surface is neither compact, nor convex

Define the Poisson Bracket

$$\{f, g\} = \sum_{1 \leq i \leq N} \frac{1}{\Gamma_i} \left(\frac{\partial f}{\partial x_i} \frac{\partial g}{\partial y_i} - \frac{\partial f}{\partial y_i} \frac{\partial g}{\partial x_i} \right)$$

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- The system is invariant under translation

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- The system is invariant under rotation

$$\Rightarrow I = \sum_{1 \leq i \leq N} \Gamma_i |z_i|^2 = \text{CST}$$

- There are three independent first integrals in involution: $H, I, P^2 + Q^2$

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- The 3-vortex problem is integrable.
- The N -vortex problem is in general not integrable when $N > 3$ (S. Ziglin 1980; J. Koiller and S. P. Carvalho 1989).

VARIATIONAL APPROACH FOR HAMILTONIAN SYSTEM

- Analogy in Celestial Mechanics
(A. Chenciner and R. Montgomery, 2000)

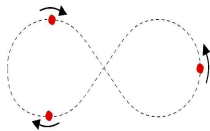


Figure 4: The eight-figure curve

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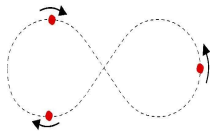


Figure 4: The eight-figure curve

- Give an example that linking techniques apply to Superquadratic Hamiltonian with physical background

Variational Formulation

- Let $L^2(\mathbb{S}^1, \mathbb{R}^{2n})$ denote the set of $2N$ -tuples of 2π periodic functions which are square integrable. The Fourier expansion hence exists, i.e., for $z \in L^2(\mathbb{S}^1, \mathbb{R}^{2N})$,

$$\mathbf{z} = \sum_{k \in \mathbb{Z}^{2n}} \mathbf{a}_k e^{ikt}$$

Define the norm

$$\|\mathbf{z}\|_{W^{2,p}} = \left(\sum_{k \in \mathbb{Z}} (1 + |k|^{2p}) |\mathbf{a}_k|^2 \right)^{\frac{1}{2}}$$

It has been noticed that a proper functional space for Hamiltonian system is the space $H_T^{\frac{1}{2}}(\mathbb{S}^1, \mathbb{R}^{2n})$, where

$$H_T^{\frac{1}{2}}(\mathbb{S}^1, \mathbb{R}^{2n}) = \{\mathbf{z}(t) \in H^{\frac{1}{2}}(\mathbb{S}^1; \mathbb{R}^{2n}) \mid \mathbf{z}(0) = \mathbf{z}(T)\}$$

Variational Formulation

- The space $H_{\Gamma}^{\frac{1}{2}}(\mathbb{S}^1, \mathbb{R}^{2n})$ admits the following decomposition $H_{\Gamma}^{\frac{1}{2}}(\mathbb{S}^1, \mathbb{R}^{2n}) = E^+ \oplus E^- \oplus E^0$:

$$E^+ = \text{span}\left\{\left(\sin \frac{2\pi j t}{\Gamma}\right) e_k - \left(\cos \frac{2\pi j}{\Gamma} t\right) e_{k+n}, \left(\cos \frac{2\pi j}{\Gamma} t\right) e_k + \left(\sin \frac{2\pi j}{\Gamma} t\right) e_{k+n}\right\}$$

$$E^- = \text{span}\left\{\left(\sin \frac{2\pi j}{\Gamma} t\right) e_k + \left(\cos \frac{2\pi j}{\Gamma} t\right) e_{k+n}, \left(\cos \frac{2\pi j}{\Gamma} t\right) e_k - \left(\sin \frac{2\pi j}{\Gamma} t\right) e_{k+n}\right\}$$

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- Given the vortex Hamiltonian function, we define the following functionals for variational argument,

$$\forall z(t) \in H_T^{\frac{1}{2}}(\mathbb{S}^1, \mathbb{R}^{2n}), \quad \mathcal{A}(z) = \int_0^T y \Gamma dx dt$$

$$\mathcal{H}(z) = \int_0^T H(x, y) dt$$

$$\mathcal{J}_H(z) = \mathcal{A}(z) - \mathcal{H}(z) = \int_0^T y \Gamma dx - H(x, y) dt$$

- Given $\mathbf{z} = \mathbf{z}^+ + \mathbf{z}^- + \mathbf{z}^0$, and $\Gamma_i > 0, \forall 1 \leq i \leq n$

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- One can define an equivalent norm $\|\cdot\|_E \simeq \|\cdot\|_{H_T^{\frac{1}{2}}(\mathbb{S}^1, \mathbb{R}^{2n})}$, where

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- The subspaces E^+, E^-, E^0 are mutually orthogonal not only in $H_T^{\frac{1}{2}}(\mathbb{S}^1, \mathbb{R}^{2n})$ but also in $L^2(\mathbb{S}^1, \mathbb{R}^{2n})$

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$$H_0 = \sum_{i,j=1, i < j}^N \log |z^i - z^j|^2$$

$$H_1 = \prod_{i,j=1, i < j}^N |z^i - z^j|^2$$

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where $f(\lambda) = \mu \lambda^k$, for an integer $k > 0$ fixed large enough whose value is to be precised later on.while

$$\mu = \frac{\alpha}{kT}, \quad \alpha < 2\pi$$

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- $H_0 \rightarrow H_1$ replaces collision singularity by fixed point

- $H_1 \rightarrow H_2$ ensures the compactness: the validity of Palais-Smale condition

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- 1. We show that \mathcal{J}_{H_2} possesses a critical point \mathbf{z}_{H_2} in $H_T^{\frac{1}{2}}(\mathbb{S}^1, \mathbb{R}^{2n})$ by the construction of topological linking, Standard argument then shows that this critical point is indeed a classical solution \mathbf{z}_{H_2} of the Hamiltonian H_2

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- 4. Now by taking logarithm of H_1 (which is a legal operation when $H_1 \neq 0$), \mathbf{z}_{H_1} will become, after a reparametrization of time, a relative periodic solution \mathbf{z}_{H_0} for H_0

EXISTENCE OF CRITICAL POINT FOR J_{H_2}

Theorem (Rabinowitz-Benci, 1979)

Suppose that the Hamiltonian H is of class $C^1(\mathbb{S}^1, \mathbb{R}^{2n})$ and satisfies that

1. $H(z) > 0$
2. $H(z) = o(\|z\|^2)$ when $\|z\| \rightarrow 0$
3. $\exists r > 0$ and $\mu > 2$ s.t. $0 < \mu H(z) \leq \nabla H(z), z \rangle$ when $\|z\| > r$

Then for any $T > 0$ the Hamiltonian system has a non-constant T -periodic solution.

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- This critical point is characterized by minmax method through topological linking.
- Apply this to H_2 , we can find a non-constant periodic solution \mathbf{z}_{H_2} .
- It can be proved that the corresponding critical value c satisfies that

$$c \leq (1 + \epsilon_k)^2 \pi$$

for a small ϵ_k depending on k

$$H_1 = \prod_{i,j=1, i<j}^N |z^i - z^j|^2$$

$$H_2 = \prod_{i,j=1, i<j}^N |z^i - z^j|^2 + f(I(z))$$

- Note that in our setting

$$X_{H+f(I)} = \mathbb{J}\nabla(H + f(I)) = X_H + X_{f(I)}$$

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- \mathbf{z}_{H_2} induces a relative T -periodic solution \mathbf{z}_{H_1} for H_1

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EXCLUSION OF COLLISION FOR \mathbf{z}_{H_2}

What if a Collision Happened

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- Suppose that there is a collision. It implies that $\nabla H_1 = 0$, and \mathbf{z}_{H_2} becomes a centered uniform rotation.
- The critical value satisfies that

$$\begin{aligned}c &= I_{H_2}(\mathbf{z}_{H_2}) = \int_0^T y dx - H_2(\mathbf{z}_{H_2}) dt \\&= \frac{T\omega}{2} I(\mathbf{z}_{H_2}) - T f(I(\mathbf{z}_{H_2})) \\&= \frac{T\omega}{2} I(\mathbf{z}_{H_2}) - T \frac{1}{k} f'(I(\mathbf{z}_{H_2})) I(\mathbf{z}_{H_2}) \\&= \frac{T\omega}{2} I(\mathbf{z}_{H_2}) - \frac{1}{k} \frac{T\omega}{2} I(\mathbf{z}_{H_2}) \\&= \frac{T\omega}{2} I(\mathbf{z}_{H_2}) \left(1 - \frac{1}{k}\right) \\&= m\pi I(\mathbf{z}_{H_2}) \left(1 - \frac{1}{k}\right)\end{aligned}$$

here m is number of rotation in time T

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What if a Collision Happened

- The collision cannot happen when $I(\mathbf{z}_{H_2})$ too small. If $I(\mathbf{z}_{H_2}) \leq 1$, then :

$$\begin{aligned} |\omega| &= 2 \frac{df}{dI}(I(\mathbf{z}_{H_2})) = \mu k I^{k-1} \\ &\leq \frac{\alpha}{T} < \frac{2\pi}{T} \end{aligned}$$

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- We conclude that $I(\mathbf{z}_{H_2}) > 1$.

$$c = m\pi I(\mathbf{z}_{H_2}) \left(1 - \frac{1}{k}\right) > m\pi \left(1 - \frac{1}{k}\right)$$

- Recall that

$$c \leq (1 + \epsilon_k)^2 \pi$$

Lemma

*Suppose that the solution \mathbf{z}_{H_2} that we have found **does** have a collision, then this solution must verify that T is its minimal period.*

Theorem (Palais, 1979)

(Palais's Principle of symmetric criticality) Let \mathbf{G} be a group of isometries of a Riemannian manifold \mathbf{M} and let $f : \mathbf{M} \rightarrow \mathbf{R}$ be a \mathcal{C}^1 function invariant under \mathbf{G} . Then the set Γ of stationary points of \mathbf{M} under the action of \mathbf{G} is a totally geodesic smooth submanifold of \mathbf{M} , and if $p \in \Gamma$ is a critical point of $f|_{\Gamma}$ then p is in fact a critical point of f

Theorem (Palais, 1979)

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- Let G be a finite subgroup of $O(2) \times \Sigma_N \times O(2)$. Let Λ be T -periodic loops in the configuration space of our vortex system (Note that for the vortex problem, the configuration space coincides with the phase space). Let $g = (\tau, \sigma, \rho) \in G$ acts on $z(t) = (z_1(t), z_2(t), \dots, z_n(t)) \in \Lambda$ be such that:

$$gz_i(t) = \rho y_{\sigma^{-1}(j)}(\tau^{-1}(t))$$

In the special case, let $\rho = I$, $\sigma^{-1}(j) = j - 1$, with the convention that $z_n = z_{0-1}$ $\tau^{-1}(t) = t - \frac{T}{n}$, then the group thus generated is called the **group of choreography**

Consider the simple choreography of N vortices

$$z_i(t + \frac{T}{N}) = z_{i-1}(t), \quad i = 1, 2, \dots, N$$

This gives us a solution \mathbf{z}_{H_2} that is a simple choreography

Consider the simple choreography of N vortices

$$z_i(t + \frac{T}{N}) = z_{i-1}(t), \quad i = 1, 2, \dots, N$$

This gives us a solution \mathbf{z}_{H_2} that is a simple choreography - Suppose to the contrary that \mathbf{z}_{H_2} has a collision. Then it becomes a uniform rotation with $T^* = T$. Moreover, Without loss of generality we could assume the collision involves $z_{H_2}^1$, i.e.,

$$z_{H_2}^i(t) = z_{H_2}^1(t), \quad \forall 1 \leq i \leq N$$

Now by the definition of choreography again, we see that $\forall t \in [0, T]$

$$z_{H_2}^{2i-1}(t + \frac{T(i-1)}{N}) = z_{H_2}^i(t) = z_{H_2}^1(t) = z_{H_2}^i(t + \frac{T(i-1)}{N})$$

It turns out that

$$z_{H_2}^{2i-1}(t) = z_{H_2}^i(t) = z_{H_2}^1(t)$$

- It is clear how we can define an equivalent class for vortices collided in this way. The index of vortices in one equivalent class will be a subgroup of the cyclic group S^N , thus each equivalent will at least have two elements. Dividing S^1 parameterized by $[0, T]$ into two equal parts $[0, \frac{T}{2}]$ and $[\frac{T}{2}, T)$. Now by Pigeonhole principle there must be at least two elements falling into the same part, i.e., the time gap is less or equal to $\frac{T}{2}$. In other words, any collision will imply that

$$T^* \leq \frac{T}{2}$$

In other words, the collision will lead to $m \geq 2$

- We have thus proved the following theorem:

Theorem

$\forall N \in \mathbb{N}^*$, *the identical N -vortex system has a relative periodic choreography.*

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- Is the solution the Thomson's N -polygon?...

Thank you!

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